

SHIFT CONTROL DEVICE FOR STRADDLE-TYPE VEHICLE,  
AND STRADDLE-TYPE VEHICLE

Kosugi et al.

Appl. No.: Unknown Atty Docket: FY.51421US1NP

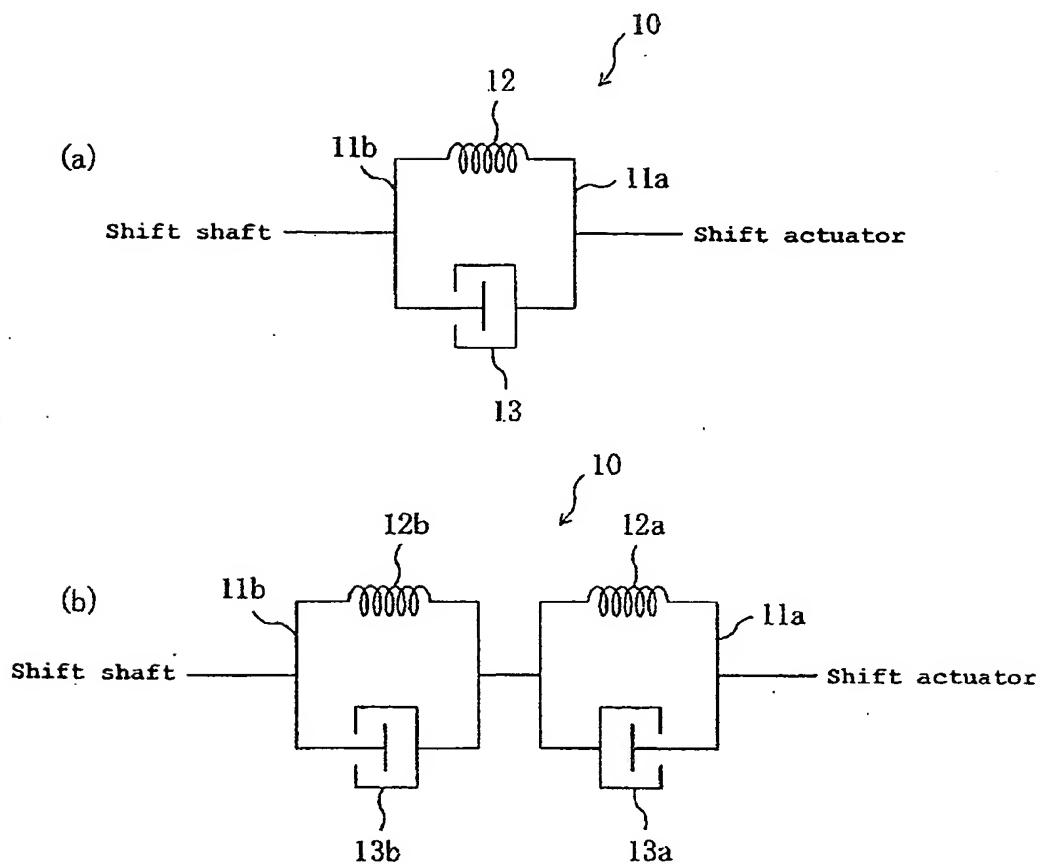


FIG. 1

SHIFT CONTROL DEVICE FOR STRADDLE-TYPE VEHICLE,  
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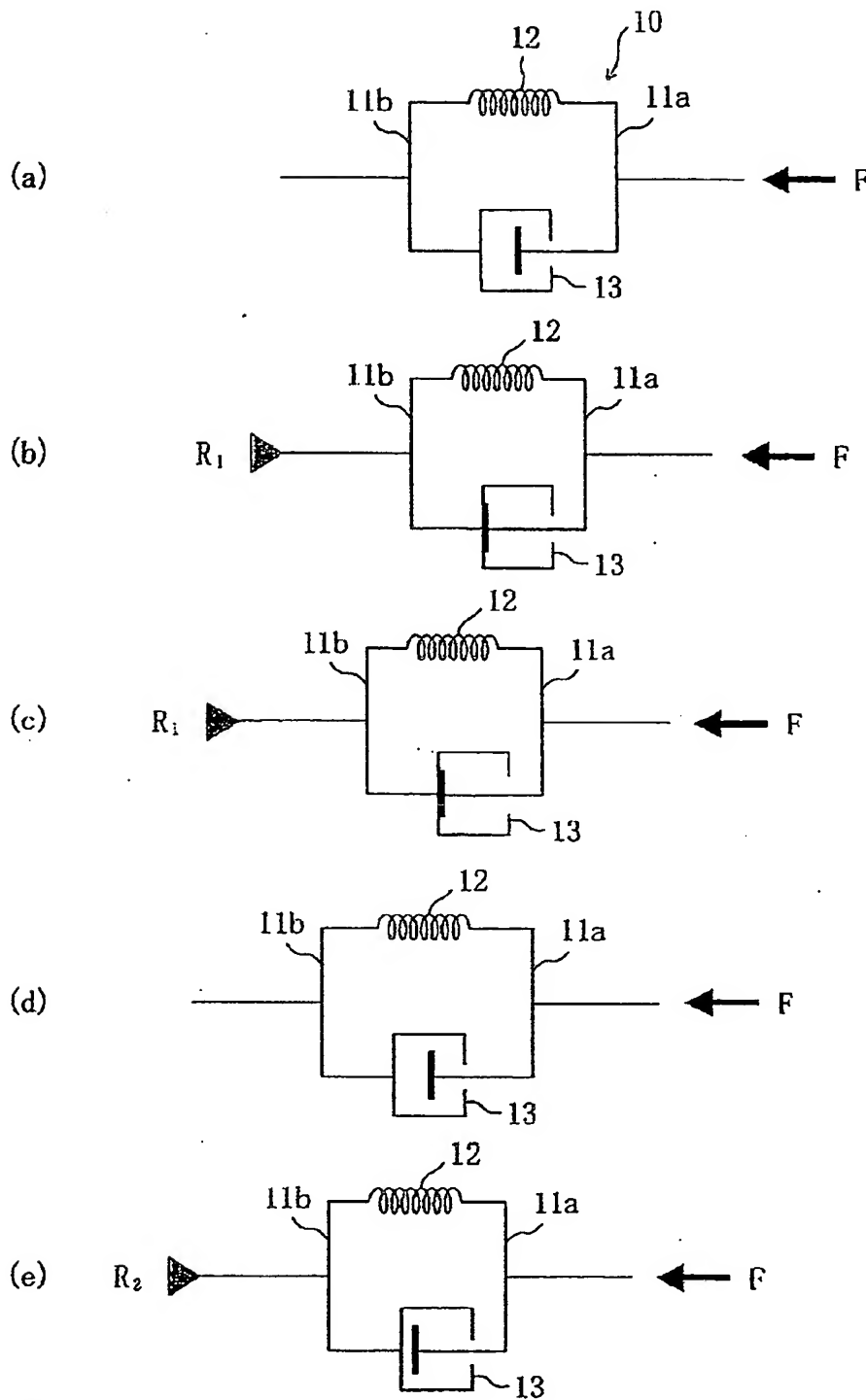


FIG. 2

SHIFT CONTROL DEVICE FOR STRADDLE-TYPE VEHICLE,  
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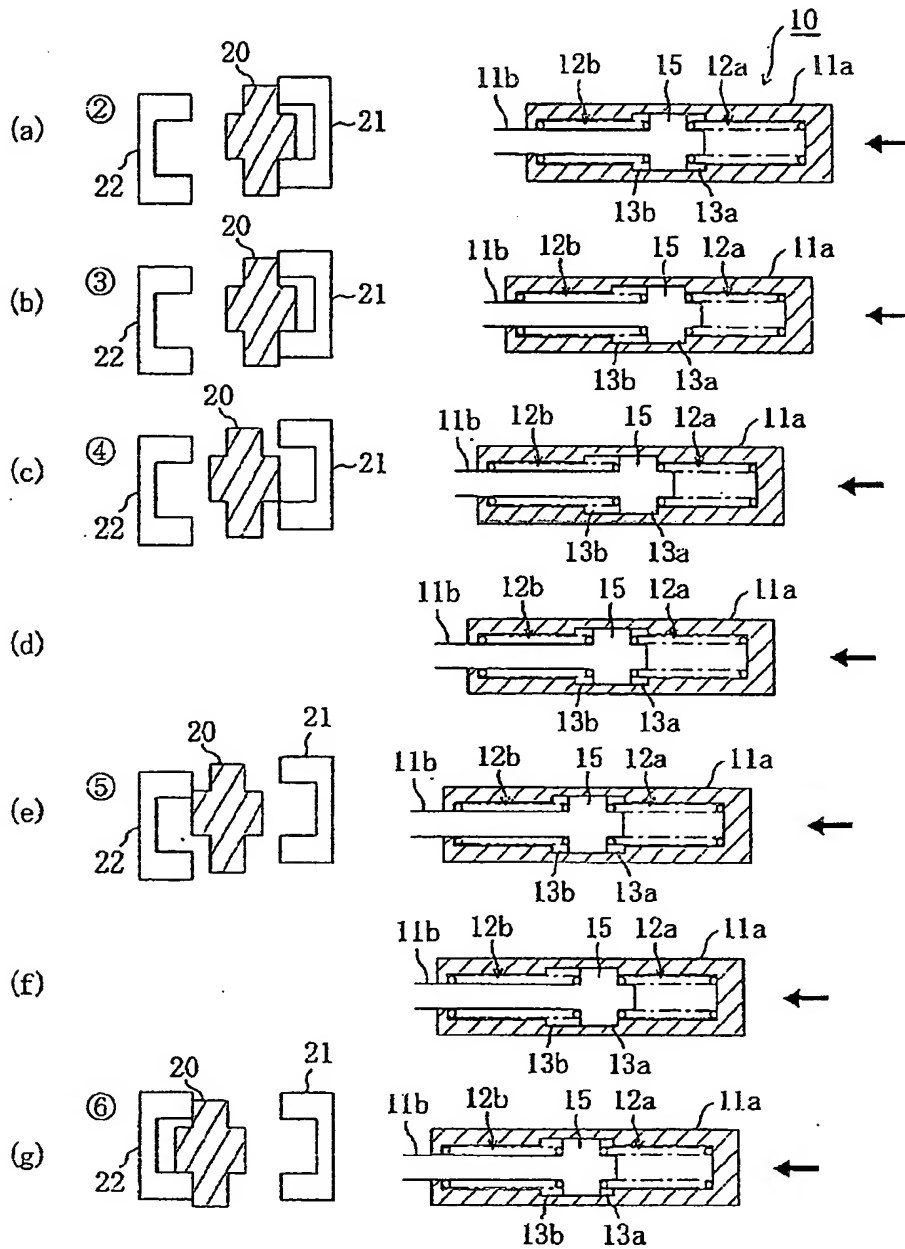


FIG. 3

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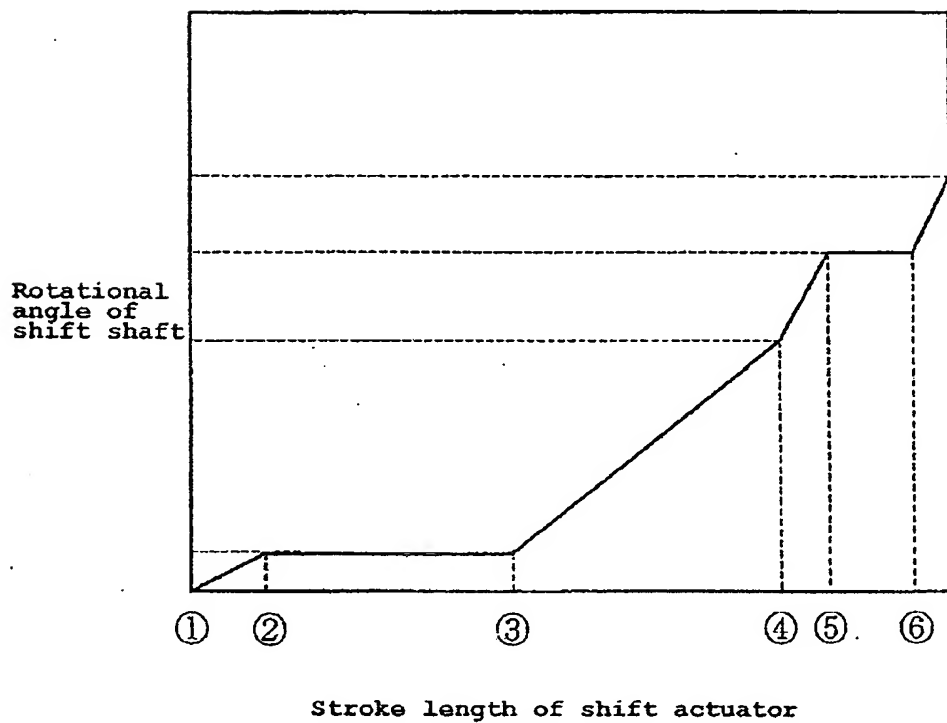


FIG. 4

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Fig. 1 consists of two cross-sectional views, (a) and (b), of a semiconductor device. Both views show a substrate 11a with a layer 11b on top. A central region 15 is defined by two vertical lines. To the left of 15 is a region 12b, and to the right is a region 12a. A layer 13a is on the right side, and a layer 13b is on the left side. In view (a), the distance from the center of region 15 to the right edge of region 12a is labeled  $L_1$ , and the distance from the center of region 15 to the left edge of region 12b is labeled  $L_2$ . In view (b), the total width of the device is labeled  $z$ . The distance from the center of region 15 to the right edge of region 12a is labeled  $x$ , the distance from the center of region 15 to the left edge of region 12b is labeled  $y$ , and the distance between the two vertical lines defining region 15 is labeled  $a$ .

FIG. 5

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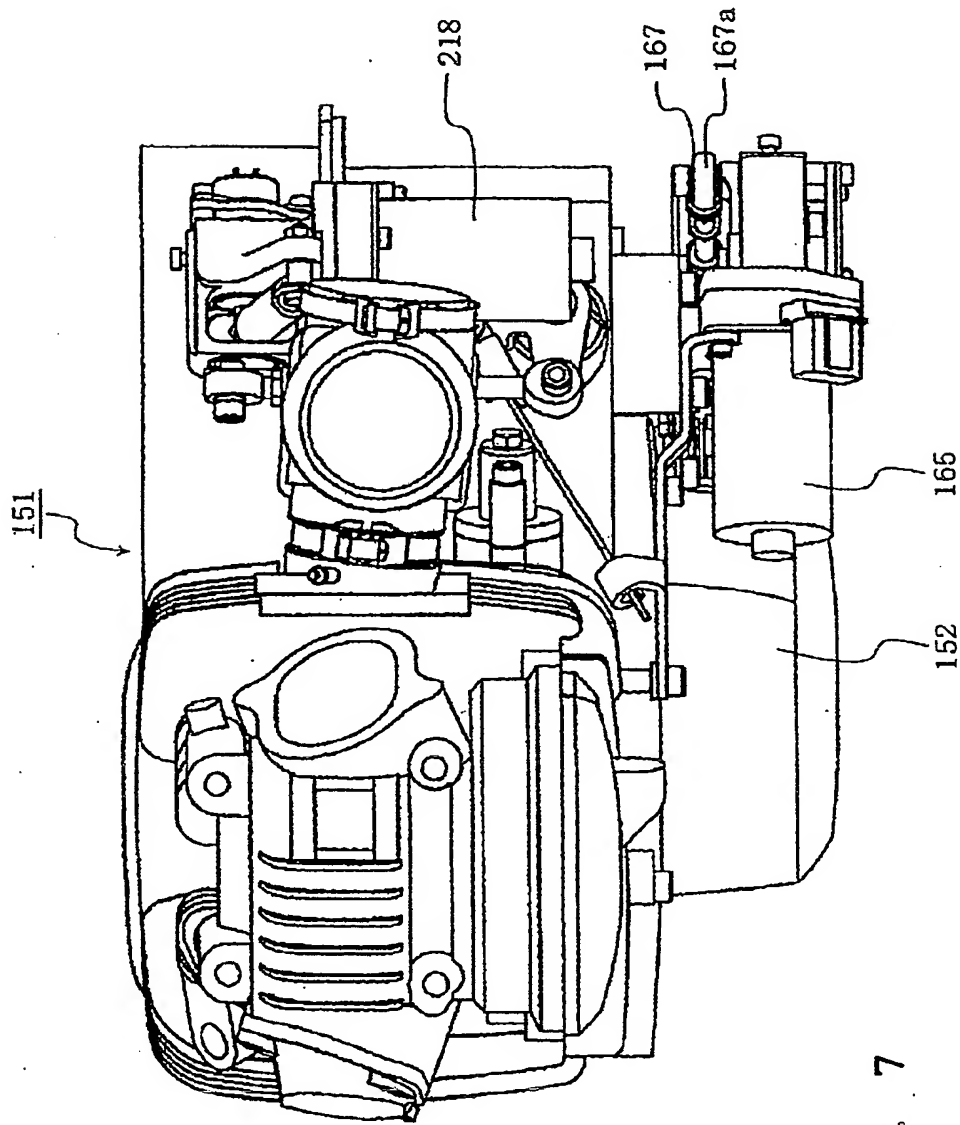


FIG. 7

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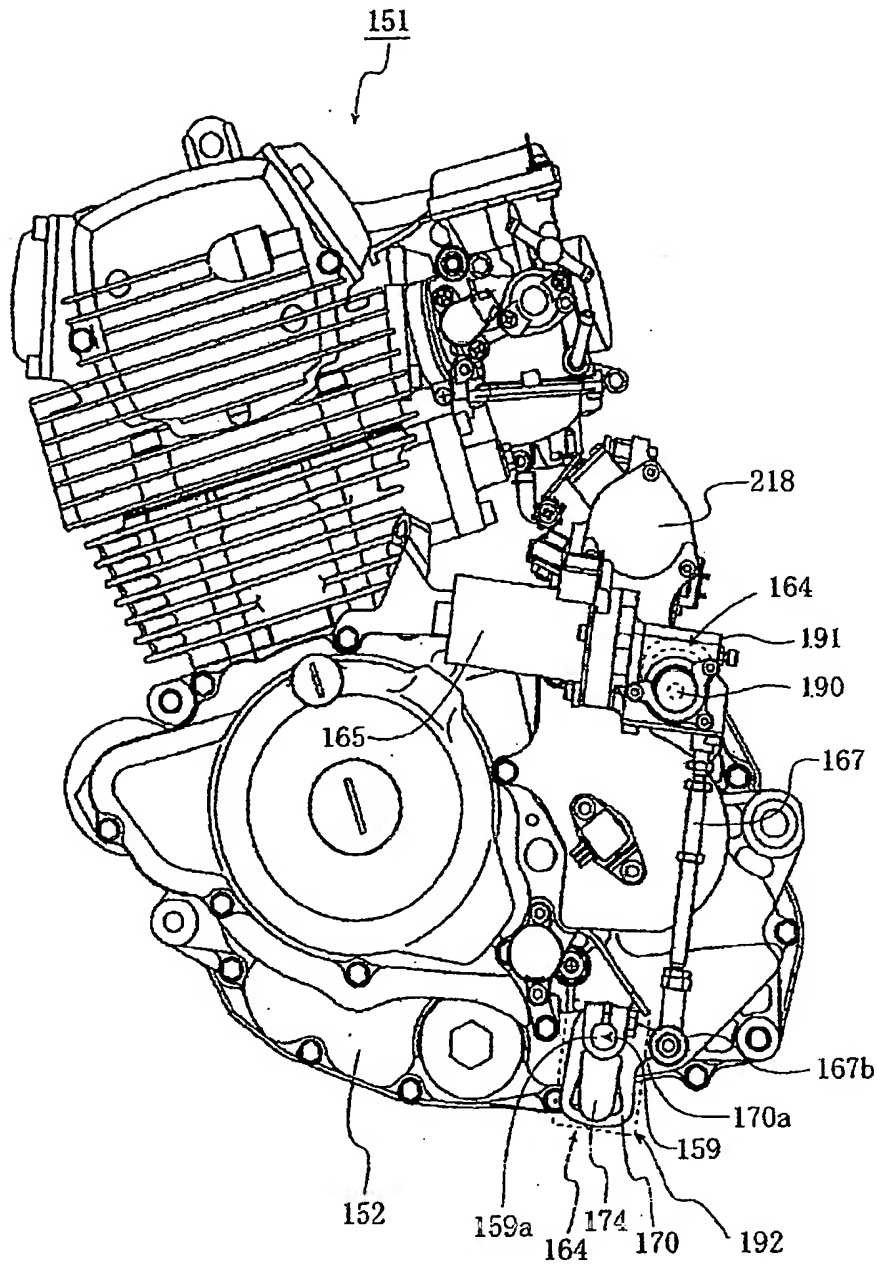


FIG. 8



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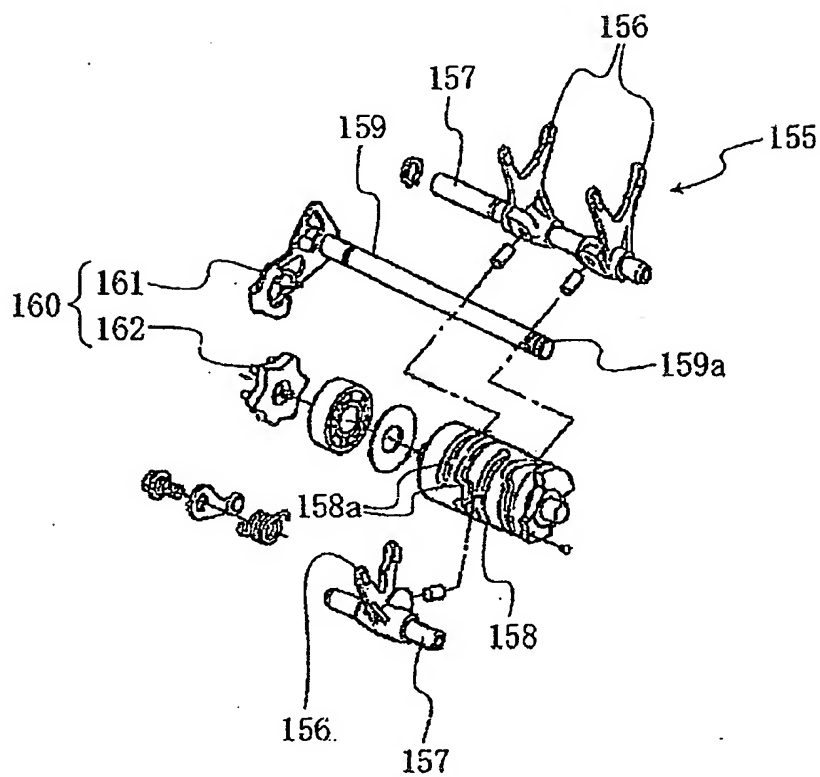


FIG. 9

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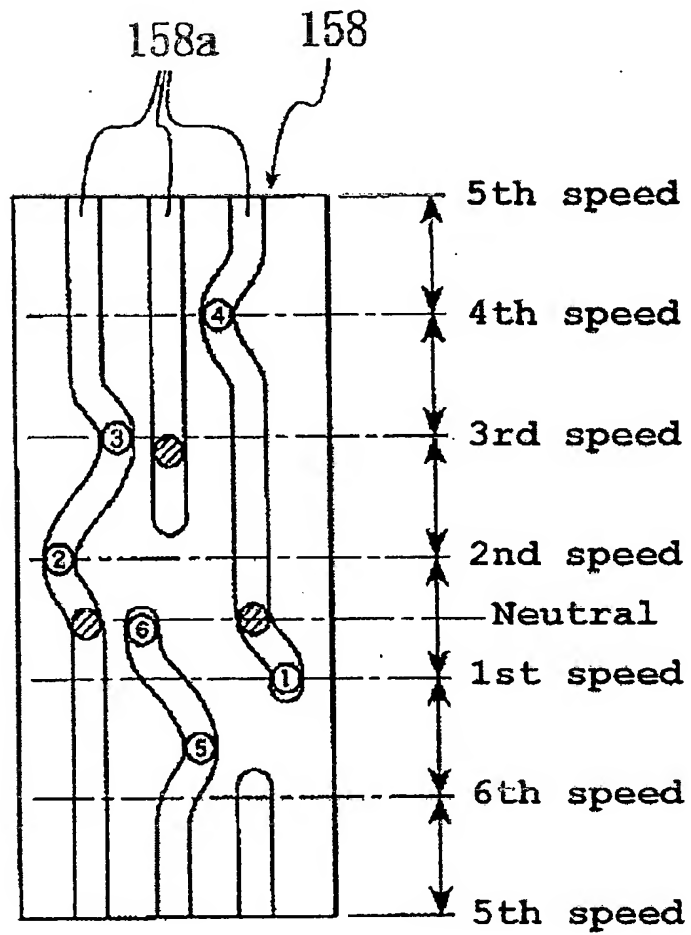


FIG. 10

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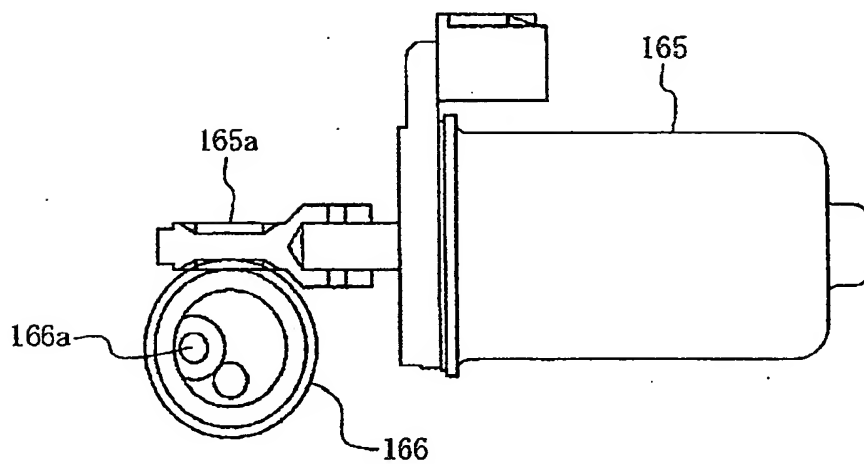


FIG. 11

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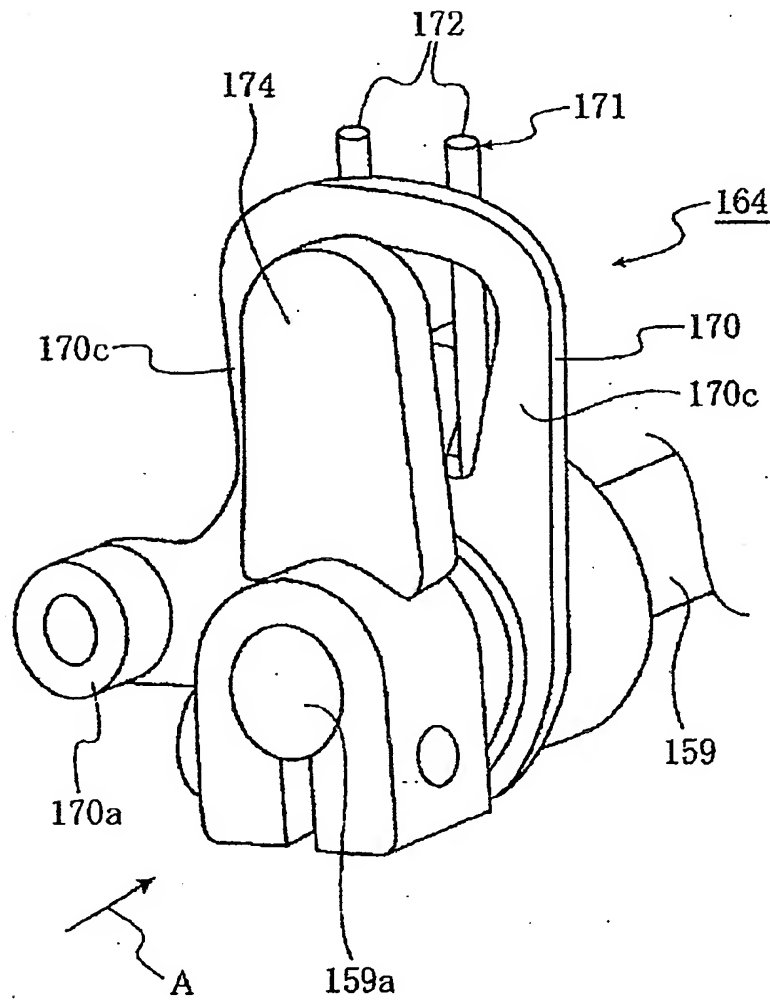


FIG. 12

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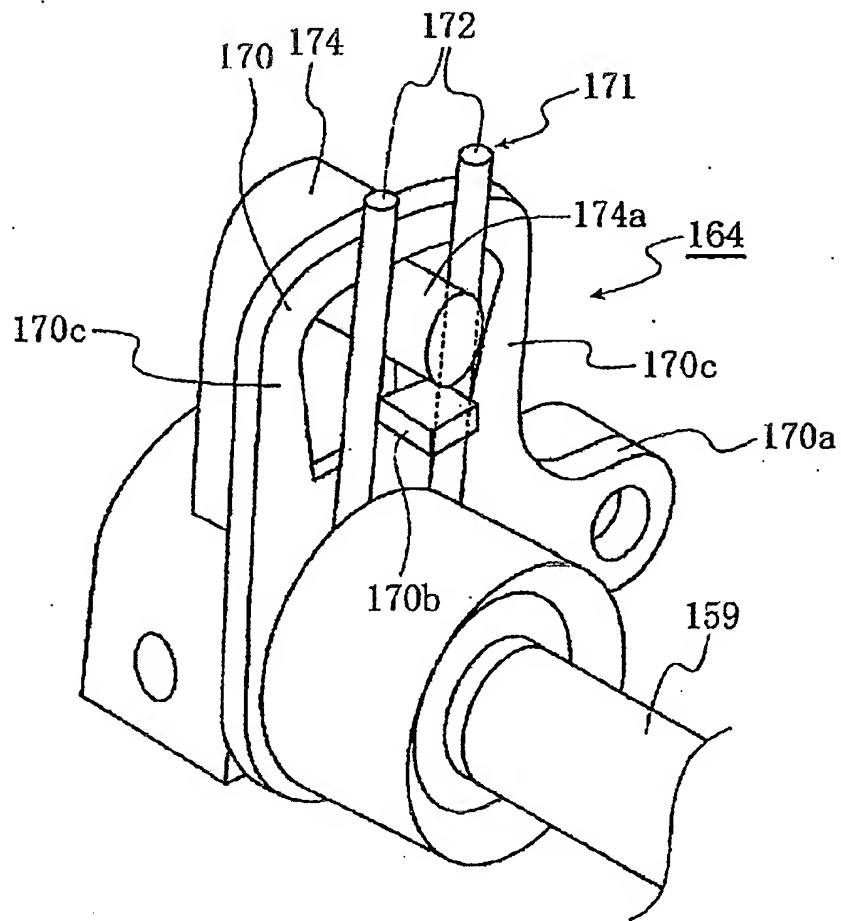


FIG. 13

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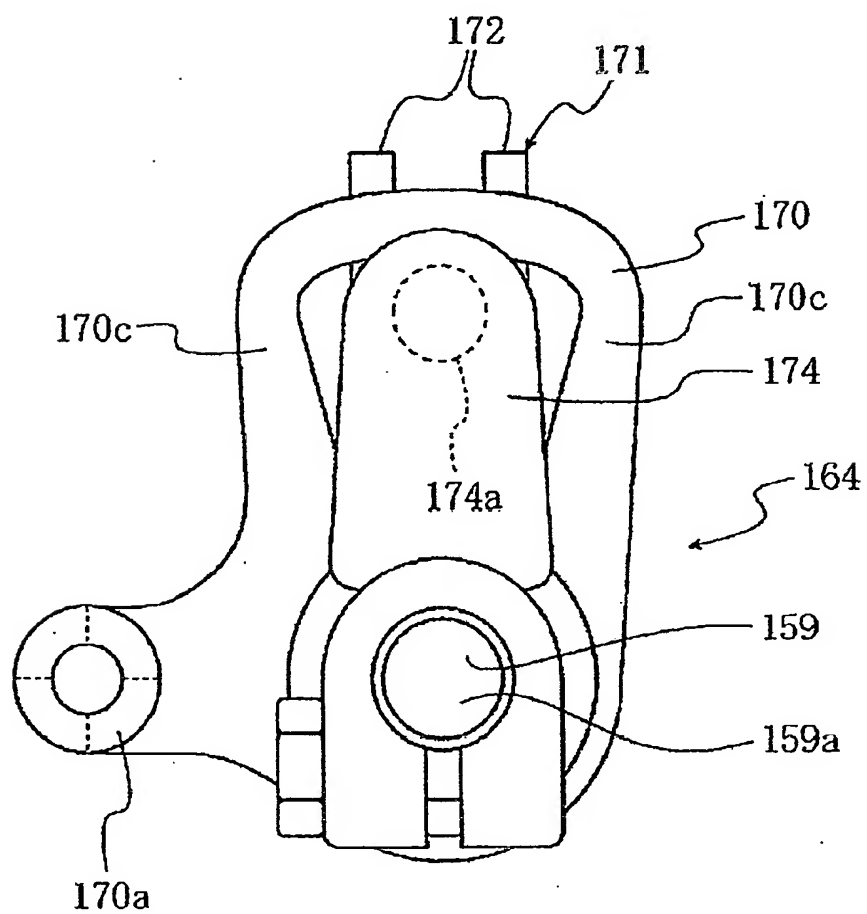


FIG. 14

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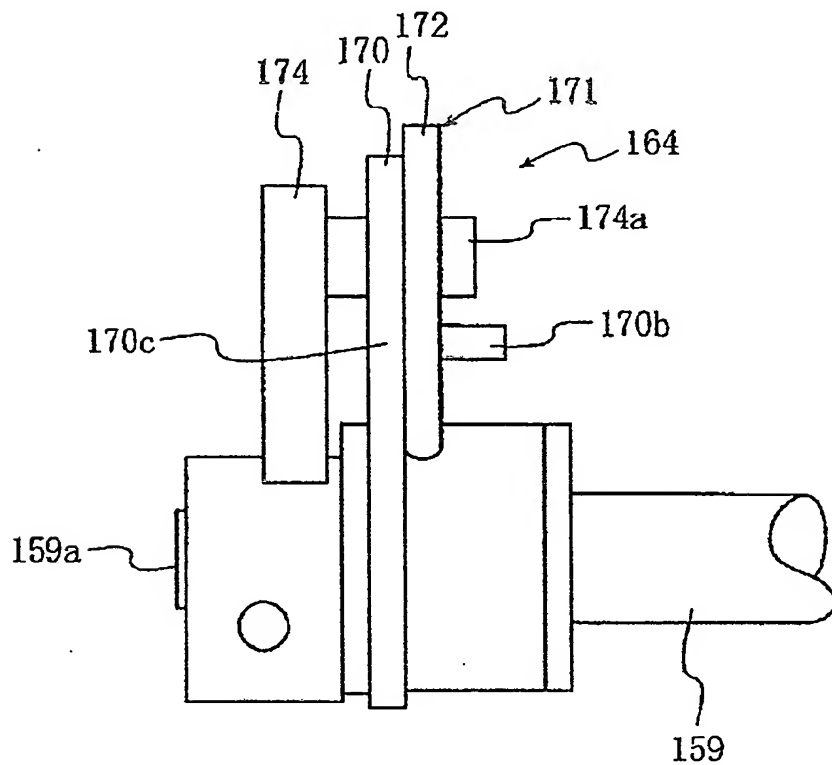


FIG. 15

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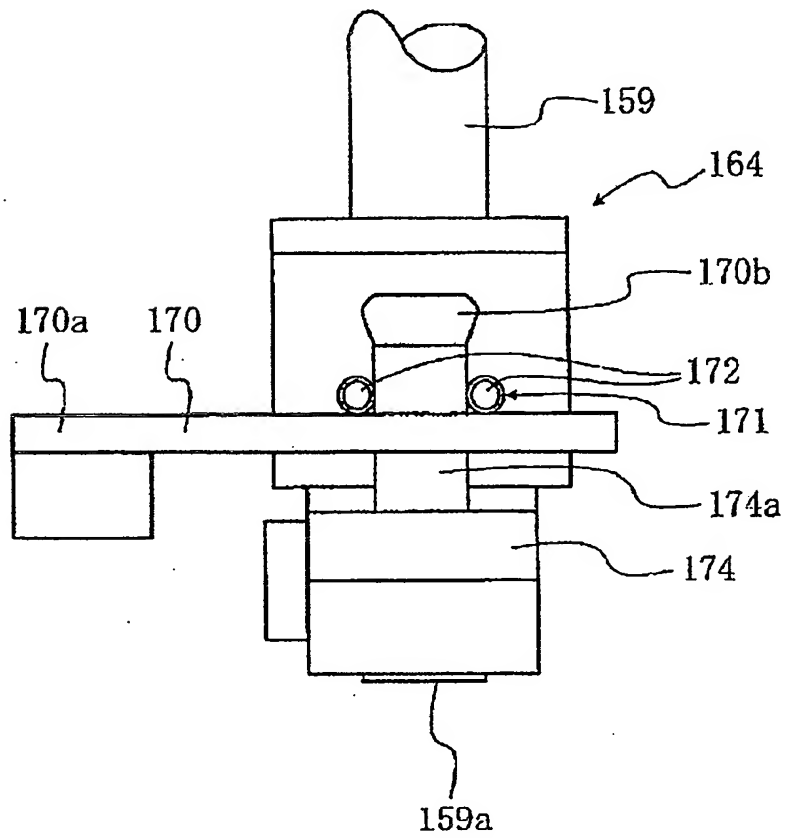


FIG. 16



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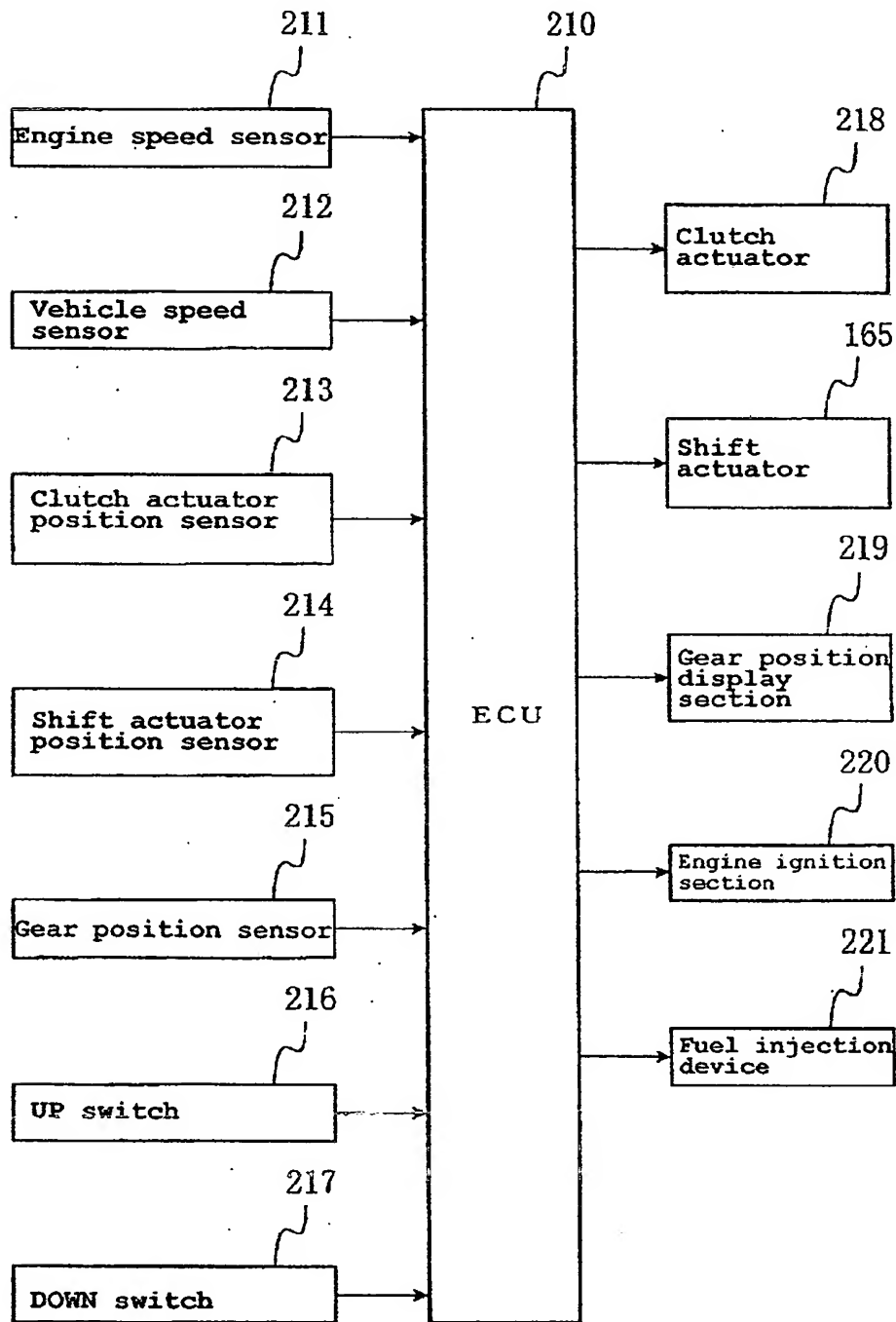


FIG. 17

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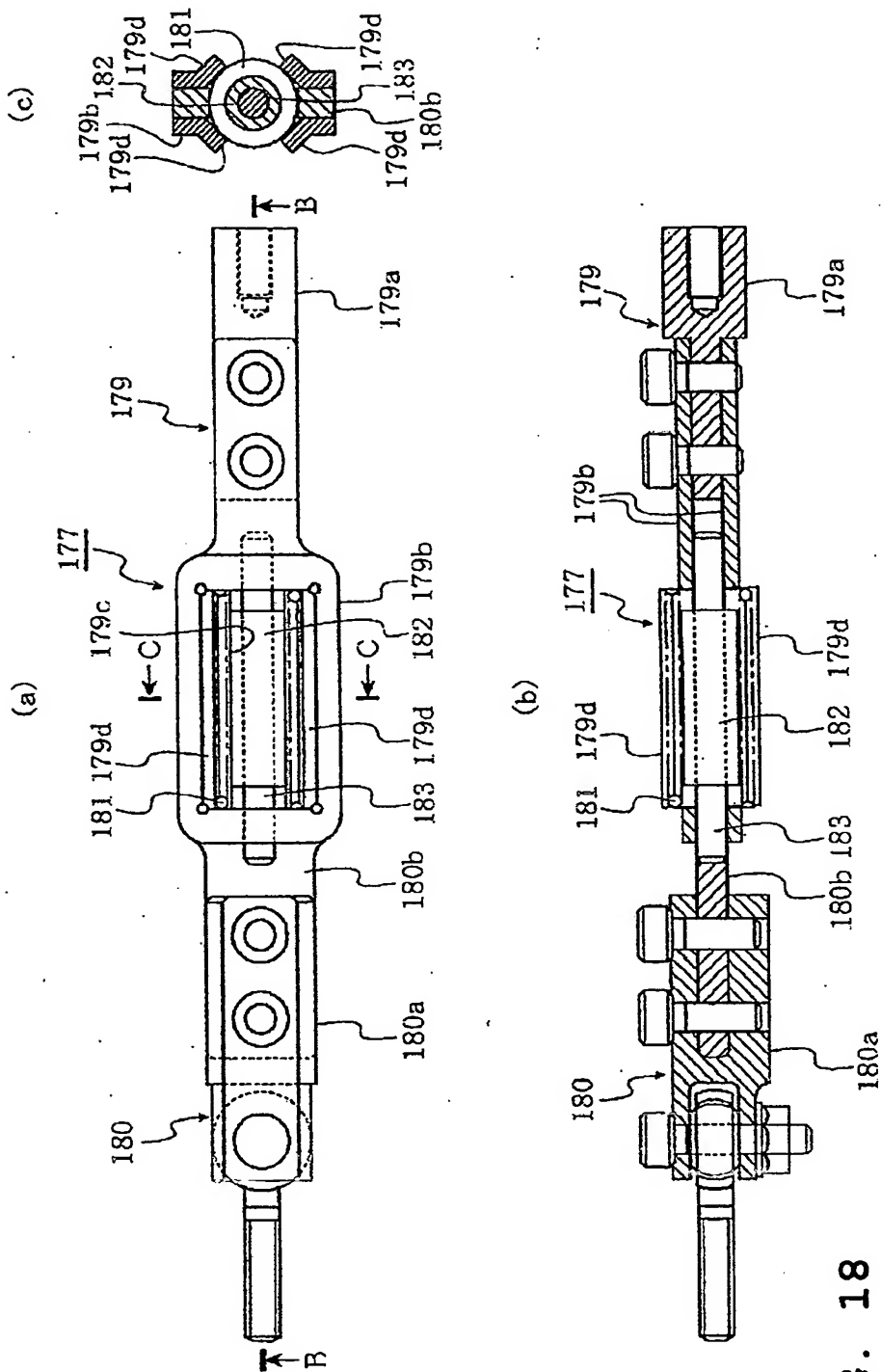


FIG. 18

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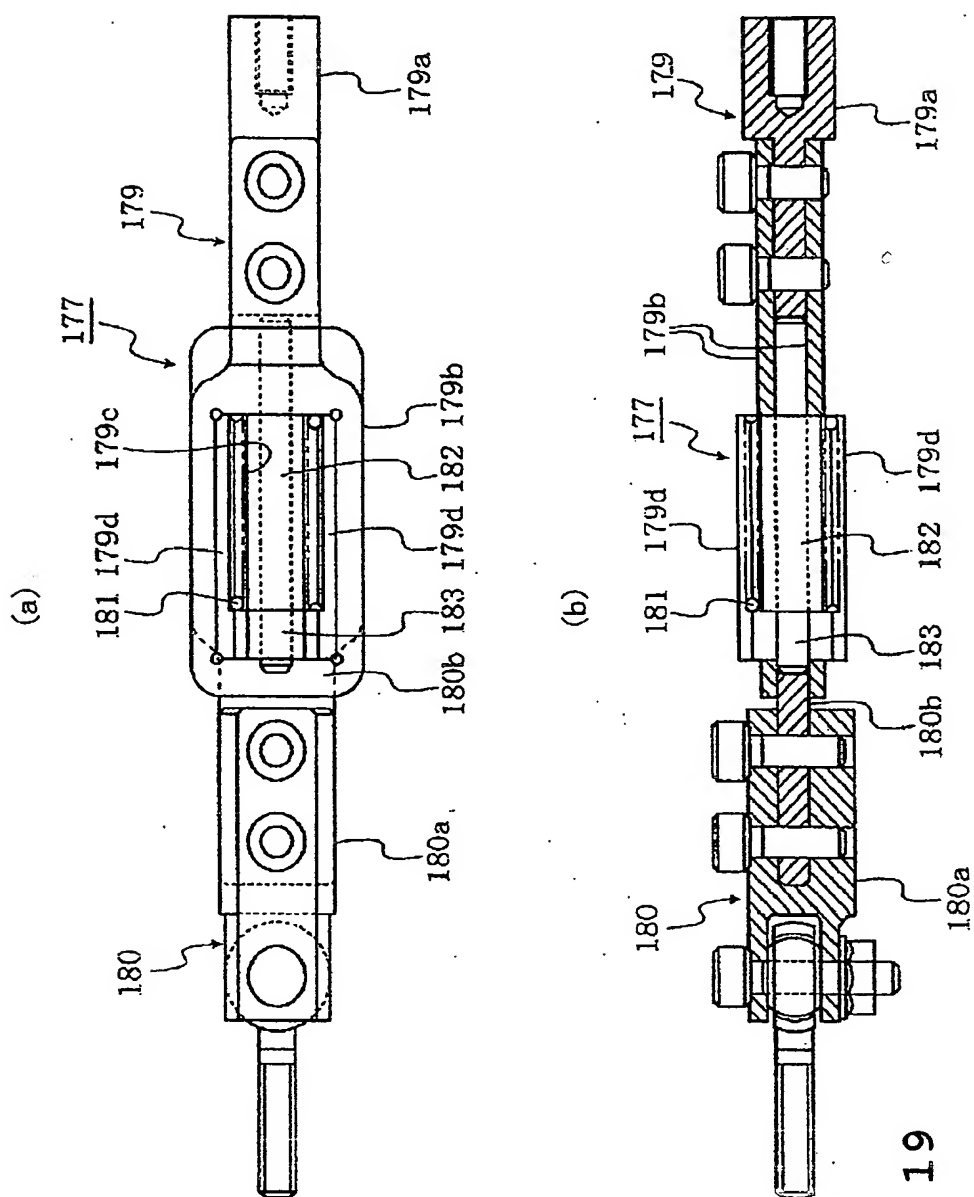


FIG. 19

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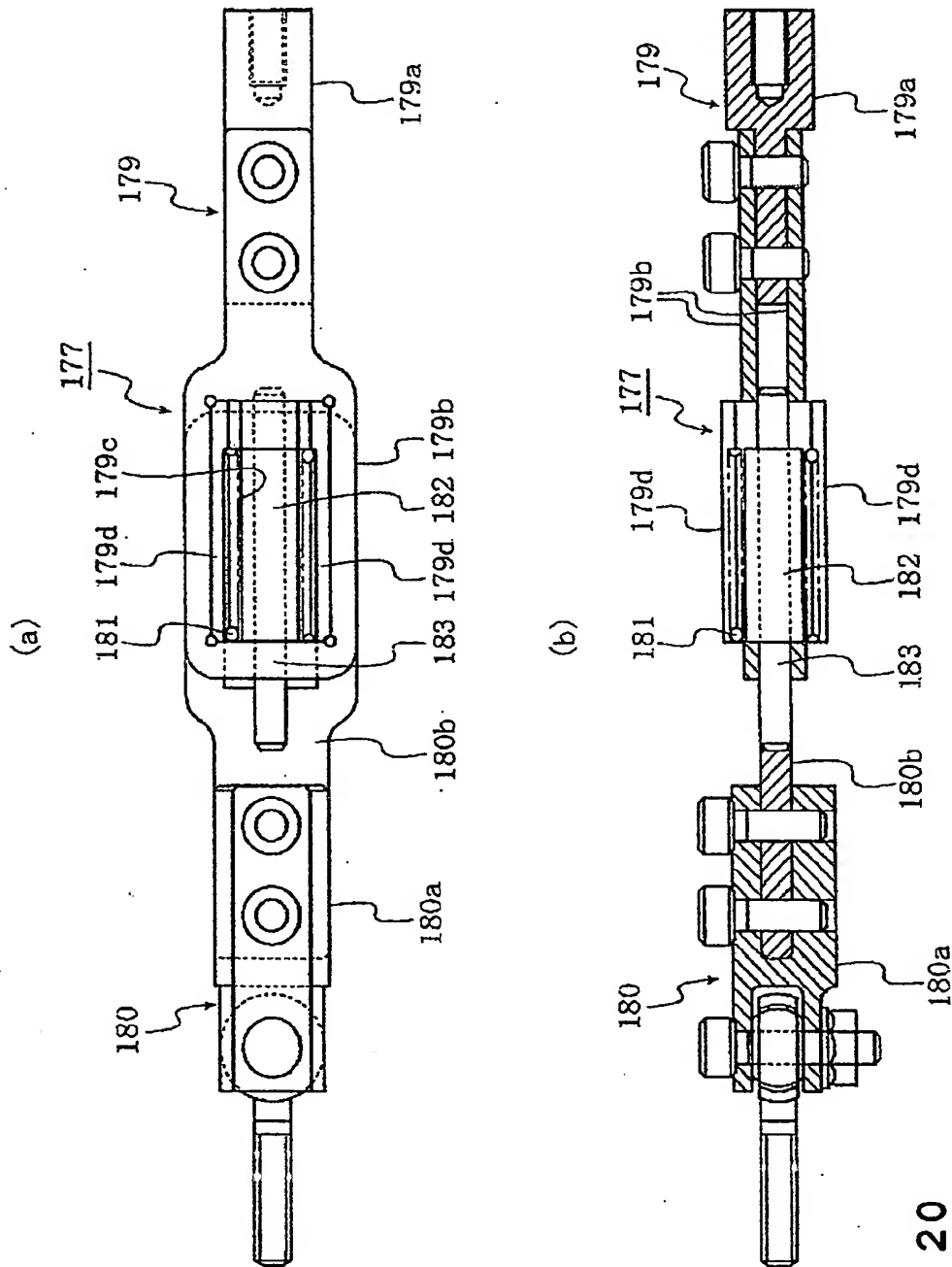


FIG. 20

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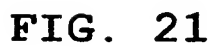


FIG. 21

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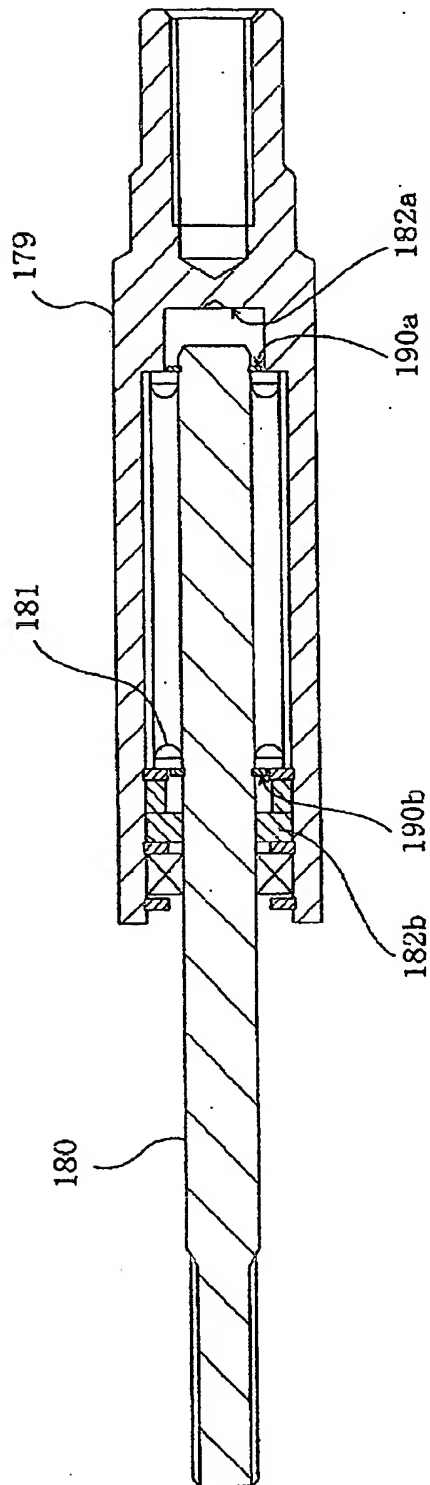


FIG. 22

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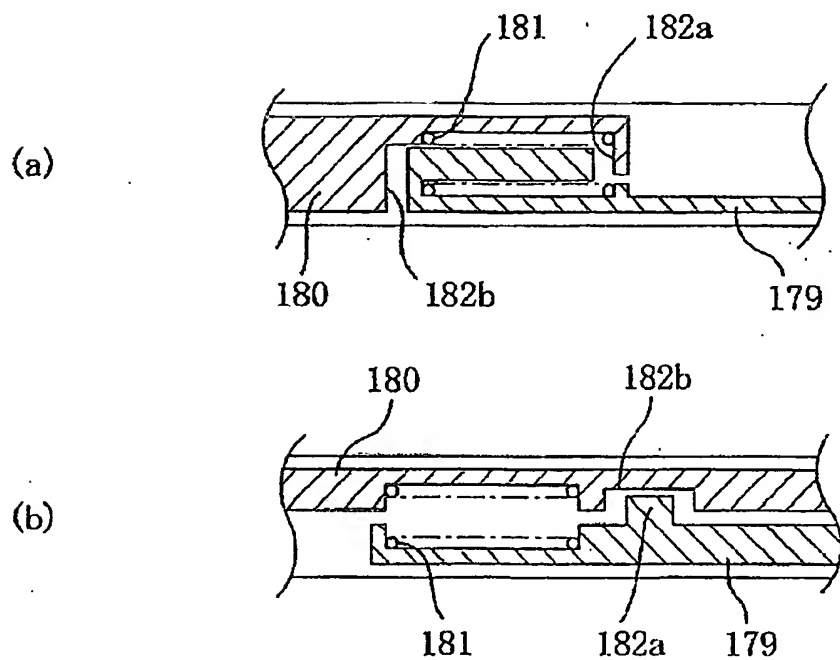


FIG. 23

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